

Distributed Systems 601.417

Asynchronous Models for Consensus

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Yair Amir Fall 21 / Lecture 5

Asynchronous Models For Consensus

Lecture 5

Further reading:

Distributed Algorithms Nancy Lynch, Morgan Kaufmann Publishers, 1996.

[FLP85] Fischer, Lynch and Paterson. Impossibility of Distributed Consensus with One Faulty Process. *Journal of the ACM,* 32, pages 374-382. April 1985.

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Distributed Consensus

Problem 1- Consensus, synchronous settings, unreliable communication: impossible.



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Distributed Consensus

Problem 1- Consensus, synchronous settings, unreliable communication : impossible.

Problem 2 - Consensus, asynchronous settings, unreliable communication : impossible

(Problem 1 is a special case of Problem 2).



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The Asynchronous Model



- · Asynchronous setting
- · Complete network graph
- Reliable FIFO unicast communication
- Deterministic processes, {0,1} initial values
- Fail-stop failures of processes are possible (remember that this is solvable in a synchronous setting)

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Solution Requirements for Consensus

- Agreement: All correct processes decide on the same value
- Validity: If a correct process decides on a value, then there was a process that started with that value
- **Termination:** All processes that do not fail eventually decide

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Impossibility Result (FLP[85])

Definitions:

- x-fair execution: executions in which all channels execute fairly, and all processes but at-most x execute fairly
- O-RCP: (0-resilient consensus protocol) a protocol that solves consensus in all 0-fair executions
- 1-RCP: a protocol that solves consensus in all
 0-fair and 1-fair executions

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FLP[85] (Cont.)

FLP: There is no 1-Resilient Consensus Protocol!

Question1: Can you think of a 0-Resilient Consensus Protocol?

Question2: what can be problematic if one of the processes may crash?

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More Definitions...

- -A finite execution α is **0-valent** if 0 is the only decision value in all extensions of α
- -A finite execution α is **1-valent** if 1 is the only decision value in all extensions of α
- α is **bivalent** if it is neither 0-valent nor 1-valent.

Lemma 1:



In any 1-Resilient Consensus Protocol there is a bivalent initial execution

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Proof of Lemma 1

- If (i1, i2, ..., in) = (0, 0, ..., 0) => decision is 0
- If (i1, i2, ..., in) = (1, 1, ..., 1) => decision is 1
- Assume that each vector (i1, i2, ..., in) is univalent
- Look at: (0, 0, ..., 0, 0), (1, 0, ..., 0, 0), (1, 1, ...
 0, 0), ..., (1, 1, ..., 1, 0), (1, 1, ..., 1, 1)
- from all the above, there exists two starting vectors that are identical except for one entry of some processor p, where v0 is 0-valent and v1 is 1-valent
- Kill p at the beginning to reach a contradiction

A Decider

A **Decider** for algorithm A consists of execution α of algorithm A and a process p such that:

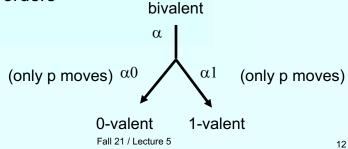
- Execution α is bivalent.
- There exists 0-valent extension α 0 of α such that the suffix after α consists of steps of p only.
- There exists 1-valent extension α 1 of α such that the suffix after α consists of steps of p only.

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Illustration of a decider

- p may receive a message and then send a message or send a message and then receive a message
- Alternatively p may receive 2 messages at different orders



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Correctness of FLP

Lemma 2:

Let A be a 1-RCP with a bivalent initial execution.
There exists a decider for A.

-- FLP is correct if Lemmas 1 and 2 are correct: Why?

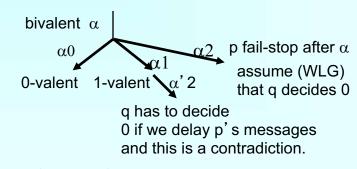
Lemma 1: In any 1-RCP there is a bivalent initial execution

Together they mean that : in any 1-RCP there exists a decider.

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Correctness of FLP (Cont.)

-- FLP is correct if Lemmas 1 and 2 are correct:

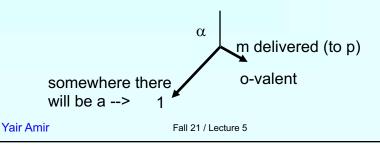


Note: only p moves in $\alpha 0$, $\alpha 1$

Proof of Lemma 2

For 1-RCP, we can delay messages from one process and still expect termination (!)

Suppose that after α , a bivalent execution, the delivery of m to p yields a univalent execution. WLG assume it yields 0-valent.



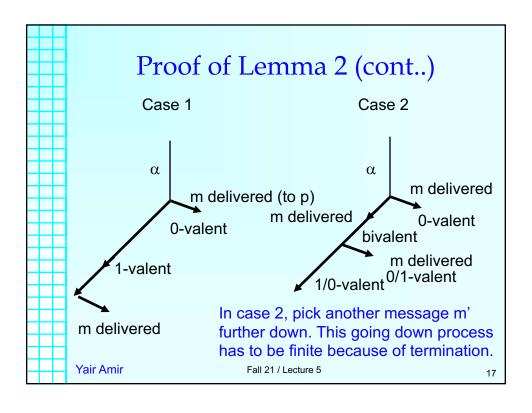
Proof of Lemma 2 (cont.)

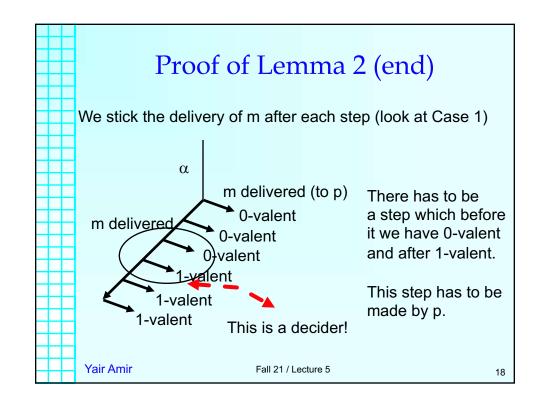
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To reach a 1-valent extension of α there are two possibilities:

- 1. m is not delivered before decision is reached
- 2. m is delivered somewhere before decision is reached

In the first case, we deliver m after the decision is reached (i.e. after reaching a 1-valent execution.)







We need to pay something in order to gain something else.

What can we pay? (what can we gain?)



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A Randomize Protocol for Consensus

A complete network graph (clique)

n - total number of processes.

f - total number of faulty processes.

Assumption: n > 5f.

This algorithm solves a more complex problem where the failure model is **Byzantine**, i.e. the failed processes can send arbitrary messages to arbitrary processes (may lie), or may fail.

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The protocol (Ben-Or variation)

Round=0; x = initial value Do Forever:

> Round = Round + 1 Step 1 Step 2



Step 1:

Send Proposal(Round,x) to all processes wait for n-f messages of type Proposal(Round,*) if at least n-2f messages have the same value v then x = v (that value)

else x = undefined

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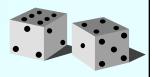
The Protocol (cont.)

Step 2:

Send Bid(Round,x) to all processes wait for n-f messages of type Bid(Round,*)

v is the real value (0/1) occurring most often and m is the number of occurrences of v

if m >= 3f+1then **Decide** (x=v) else if m >= f+1then x = v else x = random (0 or 1)



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Other Ways to Bypass The Impossibility Result

- To allow the protocol not to guarantee agreement.
- To allow the protocol not to always terminate at all correct members:
 - The Transis membership can exclude live but "slow" processes from the membership, and will reach "agreement" among the connected members.