



# Emergency Vehicle Awareness

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# Emergency Vehicle Early Warning System

- Background
- Our Approach
- Our Models
  - Client/Server - Cellular
  - Peer to Peer - RF
- Benchmarks
- Conclusion & Future Works
- Demo

**Nearly 300,000 people die each year to  
cardiac arrest**



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**30% could be saved by faster response  
times**

An aerial photograph showing a major accident scene. A red fire truck is overturned on its side in the middle of a street. Debris is scattered all around the truck. In the background, there is a building with a sign that says "Lu Dumpling" and Chinese characters. A white van is partially visible in the foreground. Several firefighters in yellow gear are visible at the bottom of the frame. The overall scene is chaotic and indicates a serious incident.

**30,000 serious accidents involving fire trucks each year**

When an accident happens



in a tunnel in South Korea.

# Background

- There are too many accidents that happen each year involving emergency vehicles
- Our current alert system (lights and sirens) has seen few advances in the past decades
- With modern wireless technology we should be able to alert drivers before they can even hear or see emergency vehicles

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# Our Approach

- Emergency Vehicles broadcast their location, and receiving vehicles can react appropriately
- How to accomplish this?
  - Client / Server - Cellular
  - Peer to Peer - RF

## Early Testing - Client / Server (Cellular)

- What does mobile data performance look like?
- How does it compare to WiFi?
- Test Application
- Lead us to three possible models

## Early Testing - Peer to Peer (RF)

- Hardware experimentation

# Connection Test Application

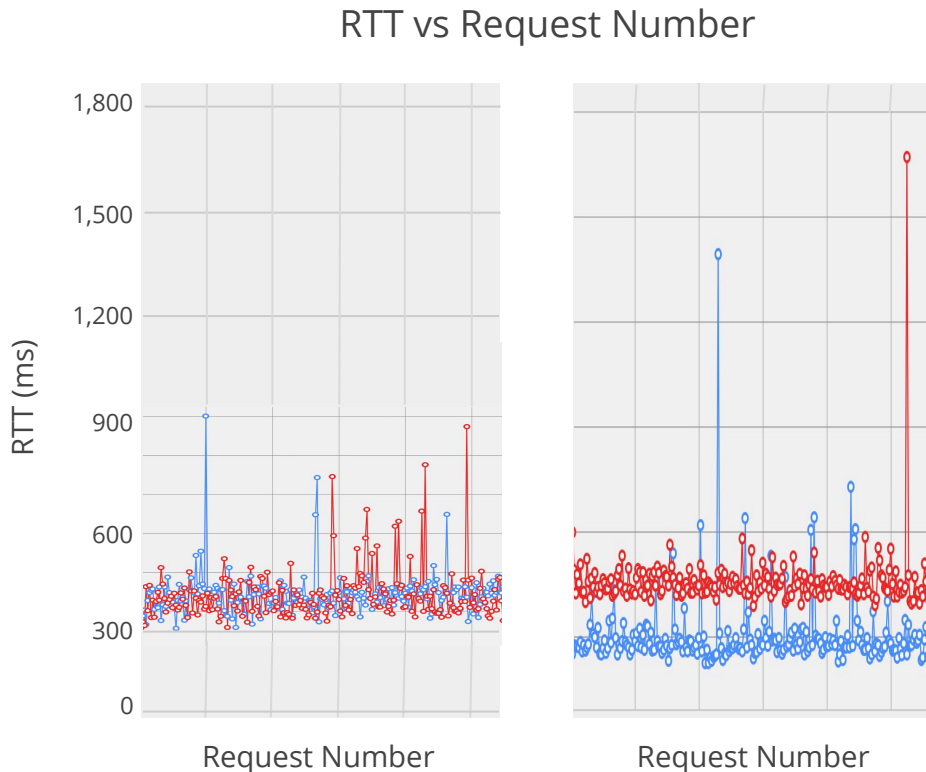
## Mobile Data

4G from Malone

Mean: 442 ms

Median: 435 ms

More variability



## WiFi

hopkins network in  
Malone

Mean: 300 - 450 ms

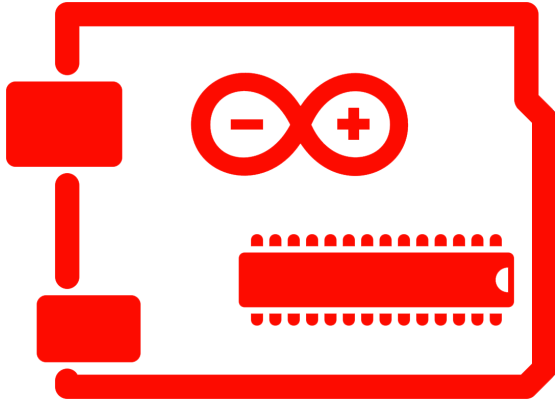
Median: 410 ms

More consistent, but  
more dependant on  
specific URL

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# Peer to Peer (RF) Method



Prototyped with an **Arduino**

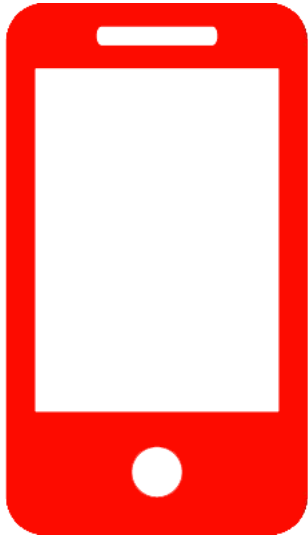
P2P between cars

Uses **smartphone** for GPS and mapping of emergency vehicles

# Peer to Peer (RF) Overview

- Decentralize our alert system for faster warning propagation
  - Similar to 802.11p, which was designed for inter-car communications
  - P2P, with alerts originating from equipped emergency vehicles
- The emergency vehicle constantly broadcasts to surroundings
  - Easily scalable
  - Very fast communication (~10ms per hop)
- All devices forward any alerts they receive, propagating messages away from their sources

# Client/Server (Cellular) Method



Deployed as a **smartphone app**

Client/Server Model

TCP-based protocol over **4G/LTE**

Central Server Alerts Drivers

# Client/Server (Cellular) overview

- Maintain a centralized list of users and their current locations
  - Server client model
- Emergency vehicles send their messages to the server which then alerts all users near the vehicle
- Takes advantage of existing infrastructure
  - Rely heavily on 4G/LTE coverage and future innovations to wireless infrastructure to handle communications
- Use Firebase to message all clients instead of server
- Potential to give warnings even earlier than RF

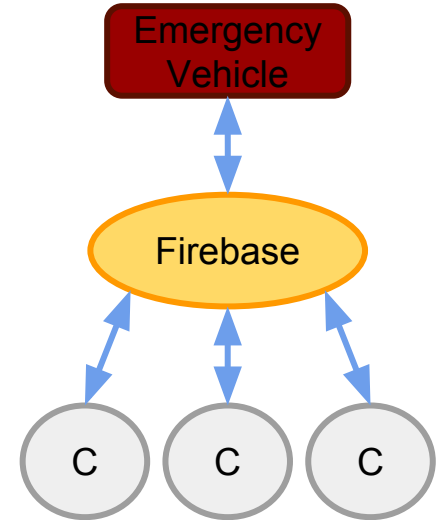


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# Discarded Strategy: Firebase-Only Approach

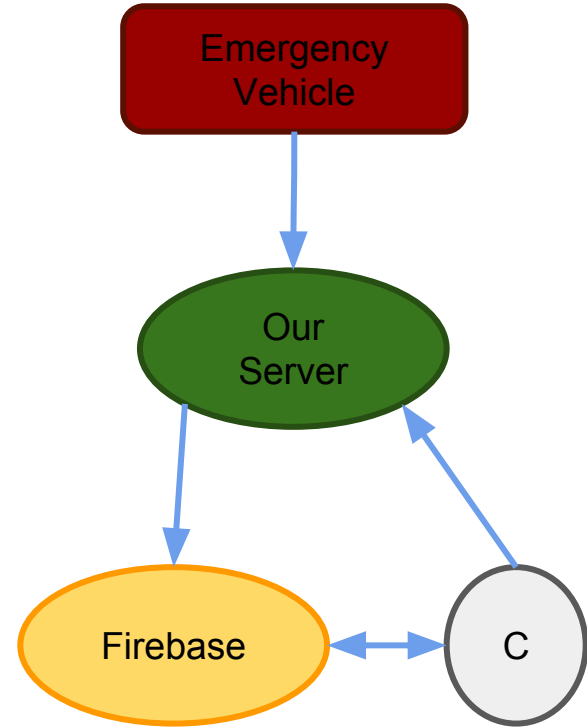
- Firebase can have users join “groups”
- We would associate a “group” with a geographical bucket
- All clients join and leave groups as their location changes
- Emergency vehicles send notifications to the nearby groups
- Jeff Dalla Tezza cautioned against this:
  - Firebase is not designed to handle the churn of our users switching groups rapidly
  - Recommends we store Firebase ID’s and directly message devices



G	G	G <sup>●</sup>
G <sup>●</sup>	G <sup>○</sup>	G
G	G	G

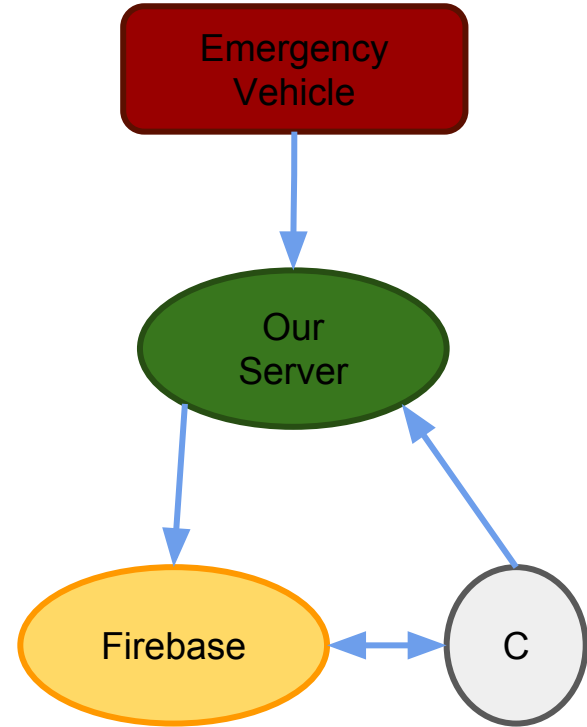
# Method: Hybrid Server/Firebase

- Clients receive a unique token from Google
- Clients pass our server the token
- Clients periodically update our server with location
- On emergency, we send appropriate tokens to Google, who then manages the notifications to clients

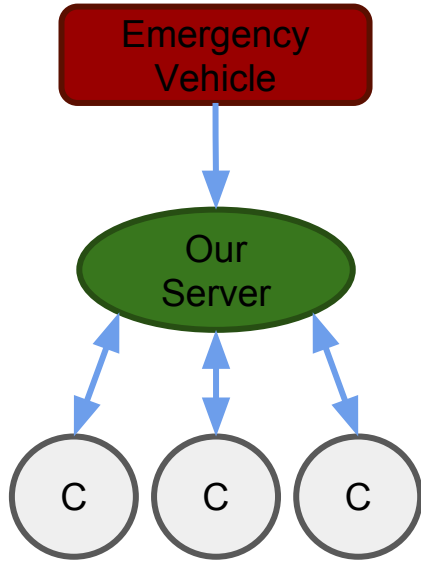


# Method: Hybrid Server/Firebase

- Pros:
  - Load on our servers is lower
    - Utilize Google's resources
- Cons:
  - Need to store location of all users
  - Additional latency from using Firebase

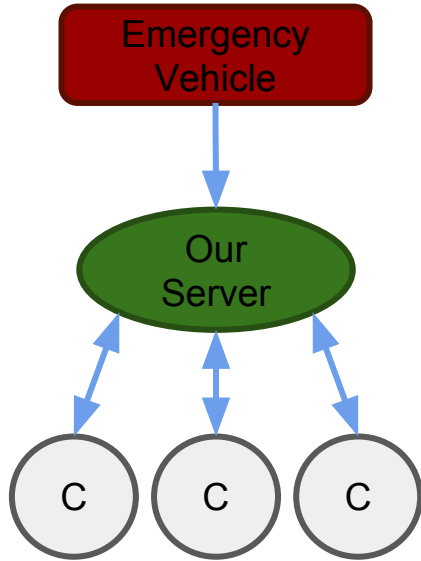


# Method: Server-Only Approach



- Emergency vehicles constantly send the server their location
- Server only stores the locations of emergency vehicles
- Clients send periodically their location, and ask, “is there an emergency in my area?”
- Clients can additionally send older locations for better heuristics on the server

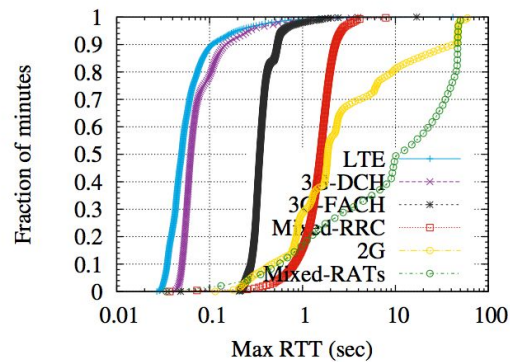
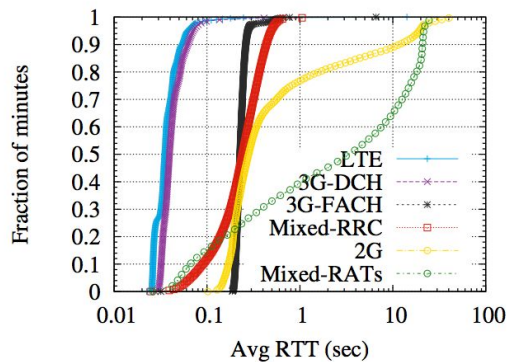
# Method: Server-Only Approach



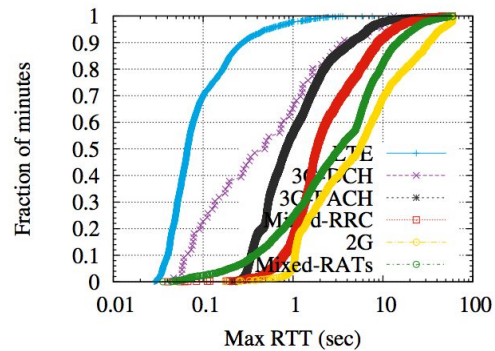
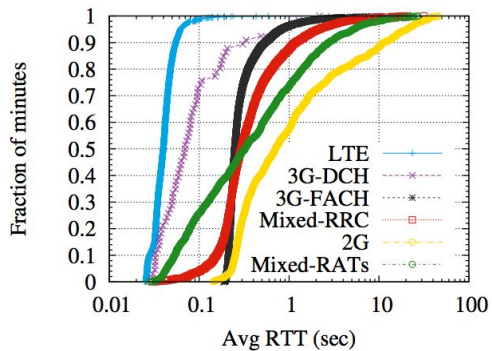
- Pros

- Lowest expected latency from server/client approaches
- We already round trip connections to the client for each update, so we might as well take advantage of that response
- Less information to store server side (more scalable!)

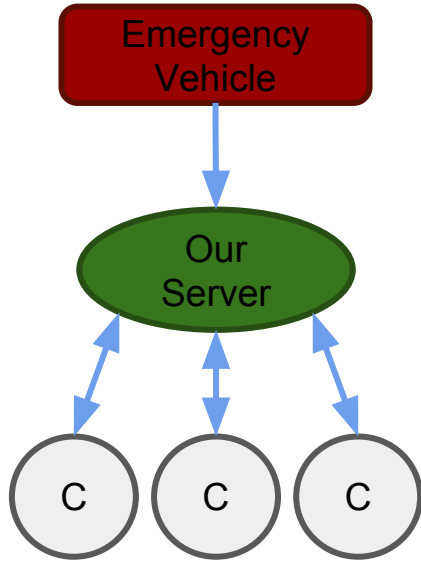
## Stationary Mobile Packet Loss



## Mobile Packet Loss in a Vehicle



## Method: Server-Only Approach (Faster?)



- Scaling to millions of cars making millions of TCP connections is impractical
- Car interaction with the server is stateless, side-effect free, and brief
- Replace HTTP with space efficient binary system
- Emergency vehicles still communicate over TCP
- Cars can use a simple UDP with retry protocol to avoid the 3-way handshake

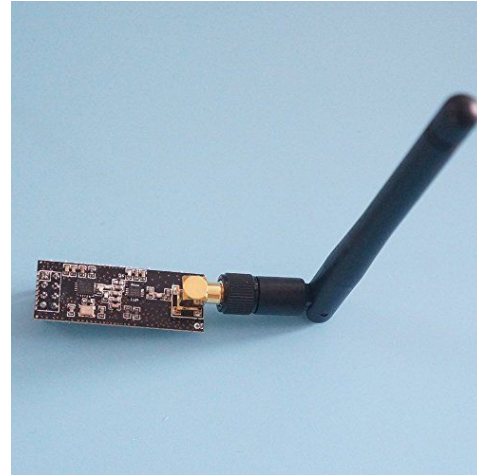
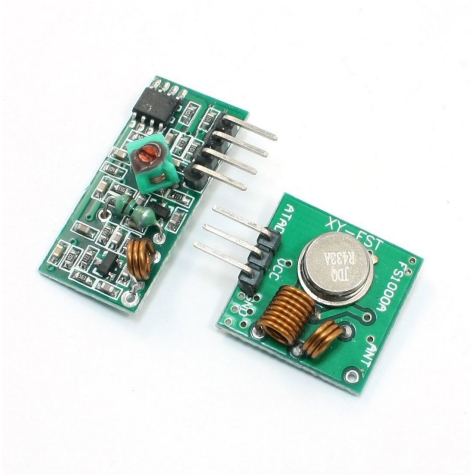


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# Peer to Peer (RF) approaches

- Tested with both 433MHz and nRF24l01 (2.5GHz) transmitters
- Found better range and library support for nRF24l01



# Peer to Peer (RF) Hardware Details

- nRF24l01 with line of sight has range of about a football field - 120 yards.  
Loss of 5-10%
- Maximum message length of 32 bytes

# RF24 Details

- Used the RF24 library by TMRh20
- Library supports reads, writes, multiple channels
- Library supports IP-like addressing & mesh network, but overhead was too high for nodes in motion

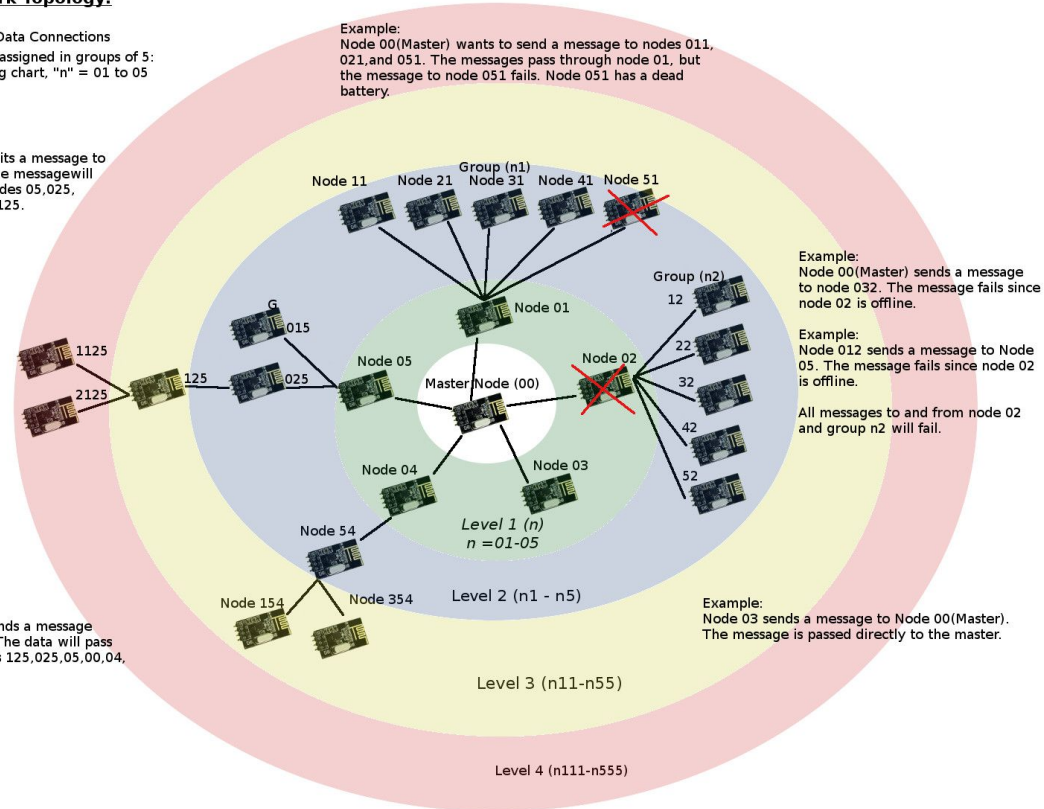
## RF24 Network Topology:

Lines — = Data Connections  
Addresses are assigned in groups of 5:  
In the following chart, "n" = 01 to 05

Example:  
Node 00 transmits a message to Node 02125. The message will pass through nodes 05, 025, 0125, then to 2125.

Example:  
Node 1125 sends a message to node 054. The data will pass through nodes 125, 025, 05, 00, 04, then to 054.

Example:  
Node 00(Master) wants to send a message to nodes 011, 021, and 051. The messages pass through node 01, but the message to node 051 fails. Node 051 has a dead battery.



# Peer to Peer (RF) Protocol

- Emergency vehicles create alerts, send them out via broadcast
- Each created message has an ID and a TTL
- Messages that are received by civilian vehicles are retransmitted with probability  $1/(2^n)$ .  $n$  = times message has been retransmitted
  - In a busy environment, civilian vehicles are expected to retransmit each message 2 times:

$$\sum_{n=0}^{\infty} \frac{1}{2^n} = 2$$

# Peer to Peer (RF) Protocol

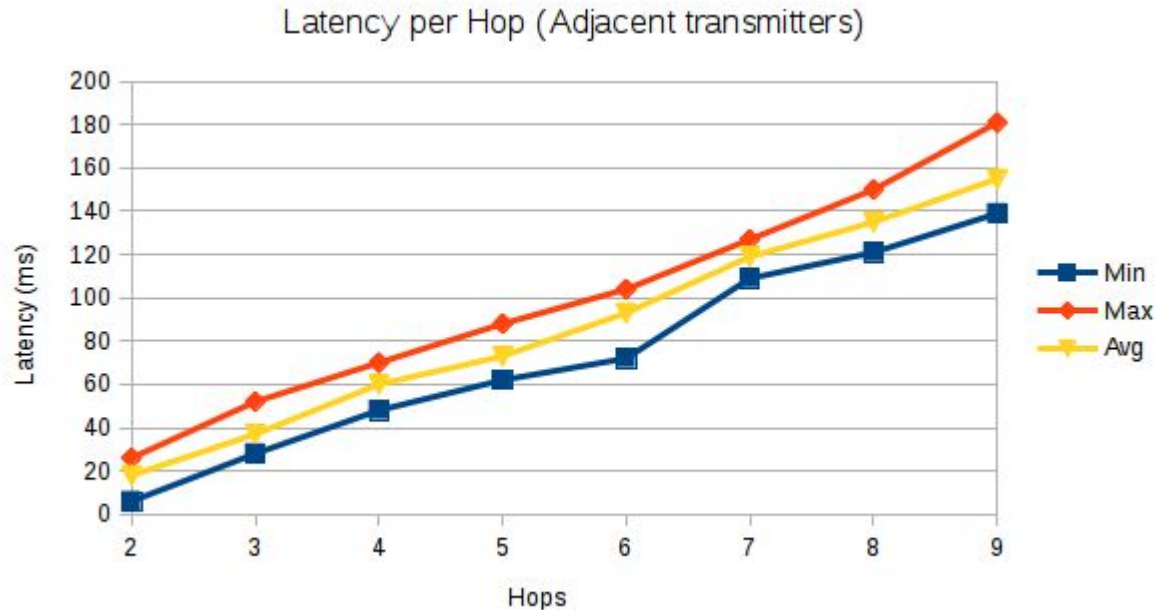
- If the network is busy, transmitters will wait a random amount of time (up to 10ms) before attempting to transmit again.
  - Based on Carrier-sense multiple access (CSMA) protocols.
- Older versions displayed message paths, knowledge matrices

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# Peer to Peer (RF) Benchmarks

- On average, about 18ms per hop
- First few hops are faster (~10ms) due to lower message traffic
- With android app, much slower due to Serial communication (baud rate = 9600)







North Charles Street

# Client/Server (Cellular) Implementation Details

- Server running in the basement of Malone right now
  - 4 core Intel Xeon 3.20GHz, 3 gigabytes of RAM
- Android App (Java)
- Python Flask Server (behind uwsgi)/Golang Server
- Redis backend (Manage location data)
- Nginx reverse proxy

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# Conclusions

- We have a version of our system that works for both sides
- The RF side may need more tuning in the future to work in crowded situations
- The server the app communicates to may eventually need to become distributed to handle increased loads or failures
- Adoption of system is likely to be a large hurdle to overcome

# Future Works

- Test in actual cars
- Smarter decisions using location on the server side
- Larger scale RF tests - play with dynamic wait periods, dynamic propagation probabilities, find/develop ways to send longer messages.
- Optimize communication between Android/Arduino, do more computation on Arduino to limit Serial communication

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***Demo***